



Efficient Approximate Predictive Inference Under Feedback Covariate Shift with Influence Functions

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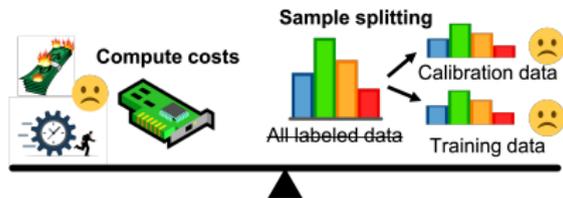
Presentation Outline

- 1** Introduction
- 2 Related Work: High-Level Overview
- 3 Technical Background and Proposed Method
- 4 Experimental Results
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Two Key Challenges in Conformal Prediction

1. Resource constraints (compute & available data)

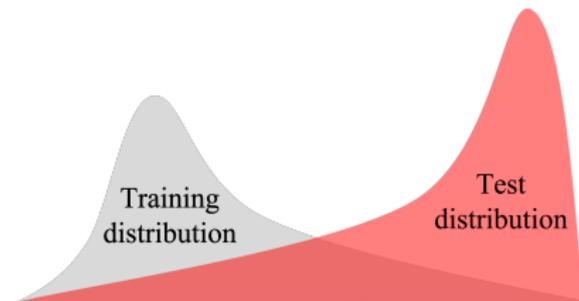
- *Computational budget*: e.g., extensive model retraining
- *Data-availability demands*: e.g., sample-splitting (which can harm model performance, especially in low data regime)



2. Data shifts

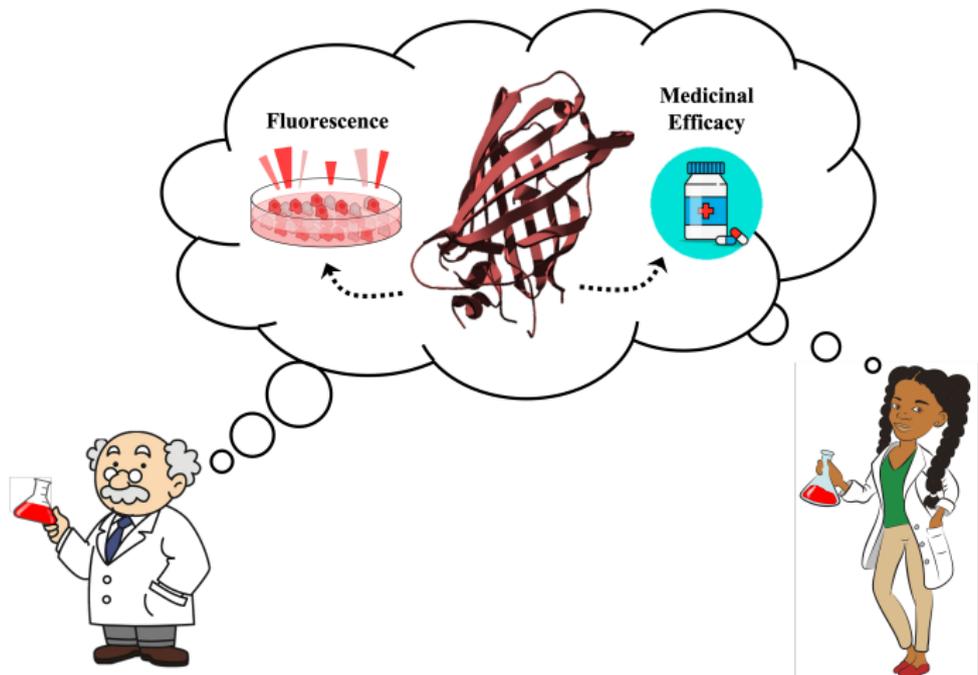
Real world data are often **not exchangeable!**

Common shifts between training & test data distributions can break standard conformal methods.



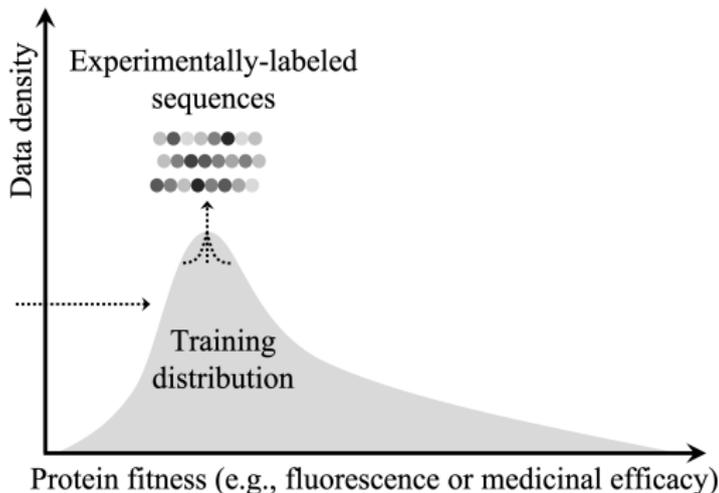
Our work (today and prior) is at the intersection of these challenges.

Biomolecular Design Setting

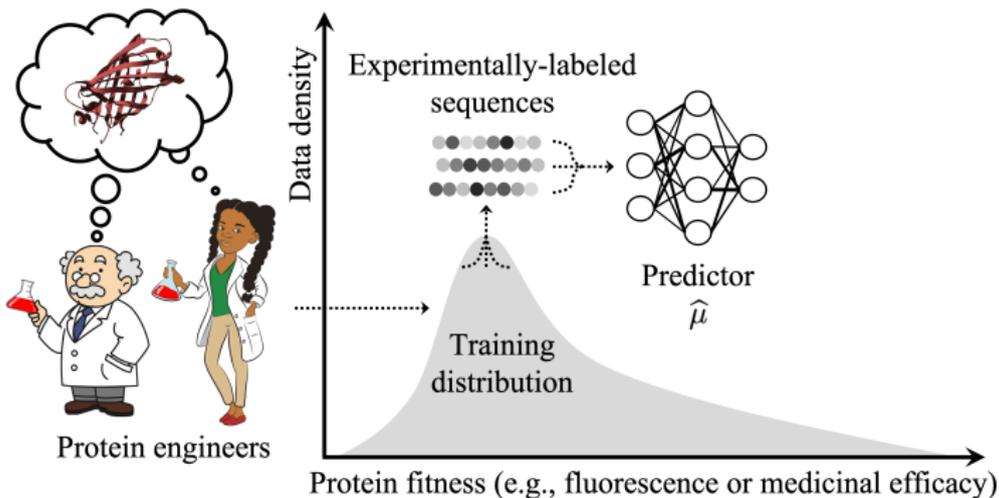


Detailed description in Fannjiang, Bates, Angelopoulos, Listgarten, and Jordan (2022)

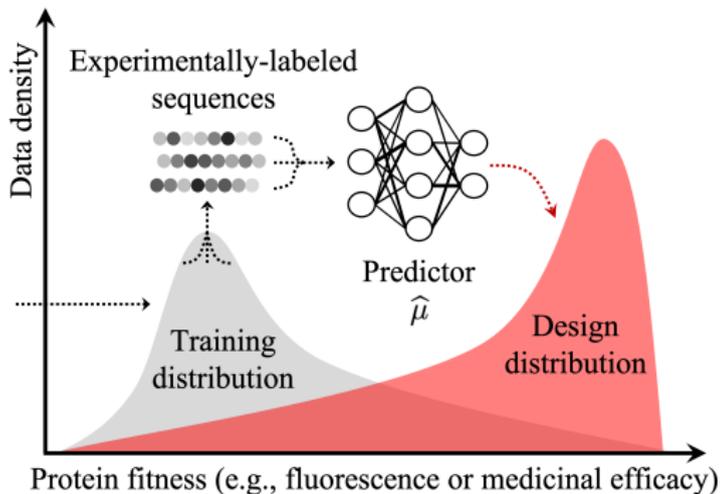
Biomolecular Design Setting



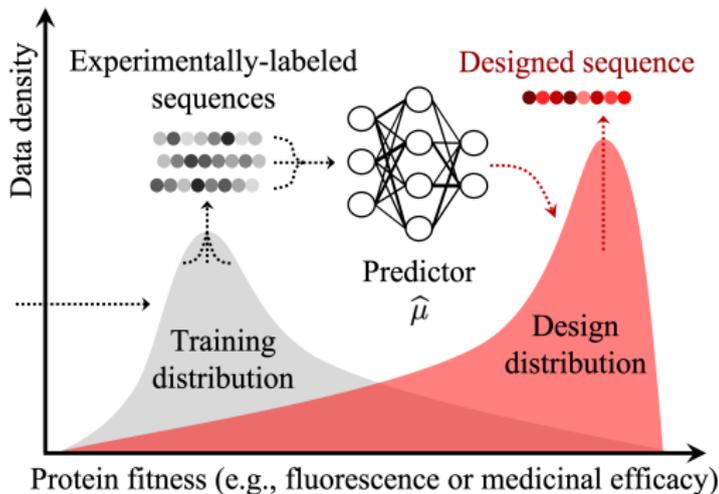
Biomolecular Design Setting



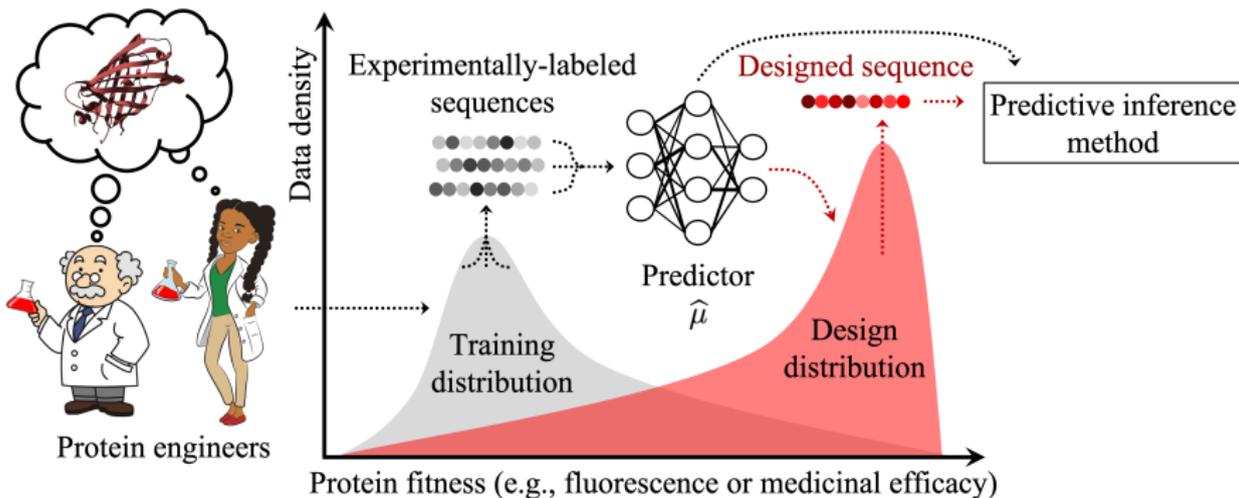
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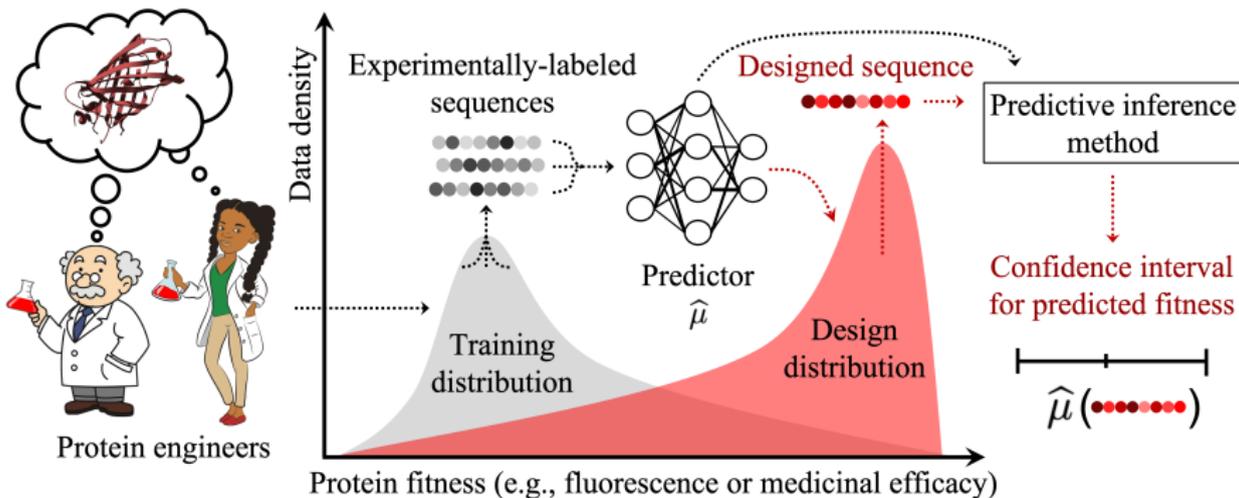
Biomolecular Design Setting



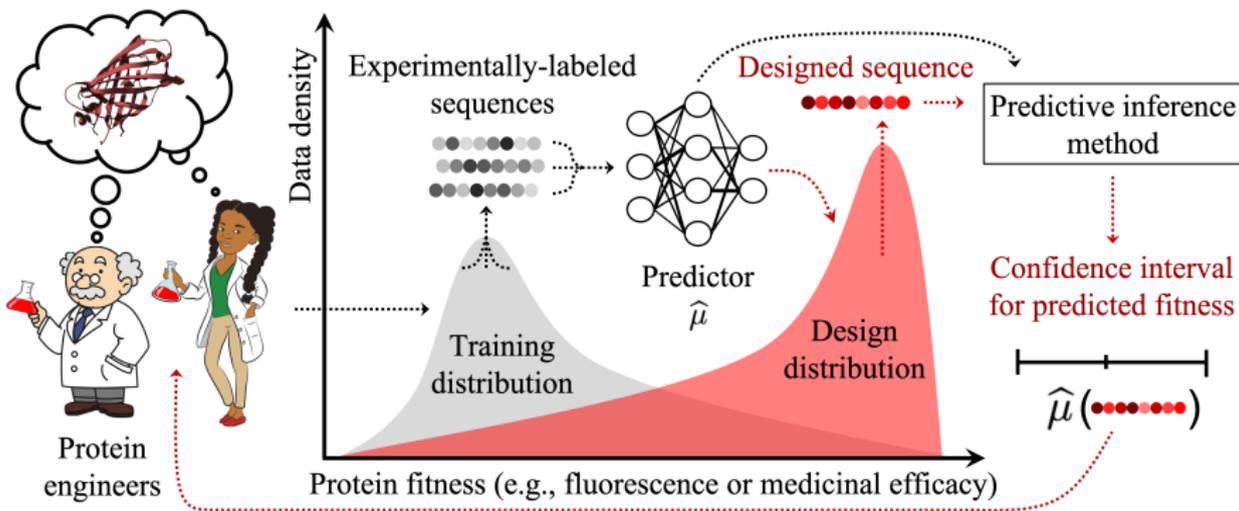
Biomolecular Design Setting



Biomolecular Design Setting



Biomolecular Design Setting



Background: Feedback Covariate Shift (FCS)

Standard conformal prediction “SCS”:

$$Z_i = (X_i, Y_i) \stackrel{\text{i.i.d.}}{\sim} P_X^{\text{train}} \times P_{Y|X}, \\ i = 1, \dots, n$$

$$(X_{n+1}, Y_{n+1}) \sim P_X^{\text{test}} \times P_{Y|X}$$



Feedback covariate shift “FCS” (One-shot biomolecular design is an instance; Fannjiang et al. (2022)):

$$Z_i = (X_i, Y_i) \stackrel{\text{i.i.d.}}{\sim} P_X^{\text{train}} \times P_{Y|X}, \\ i = 1, \dots, n$$

$$(X_{n+1}, Y_{n+1}) \sim P_{X;Z_{1:n}}^{\text{test}} \times P_{Y|X}$$



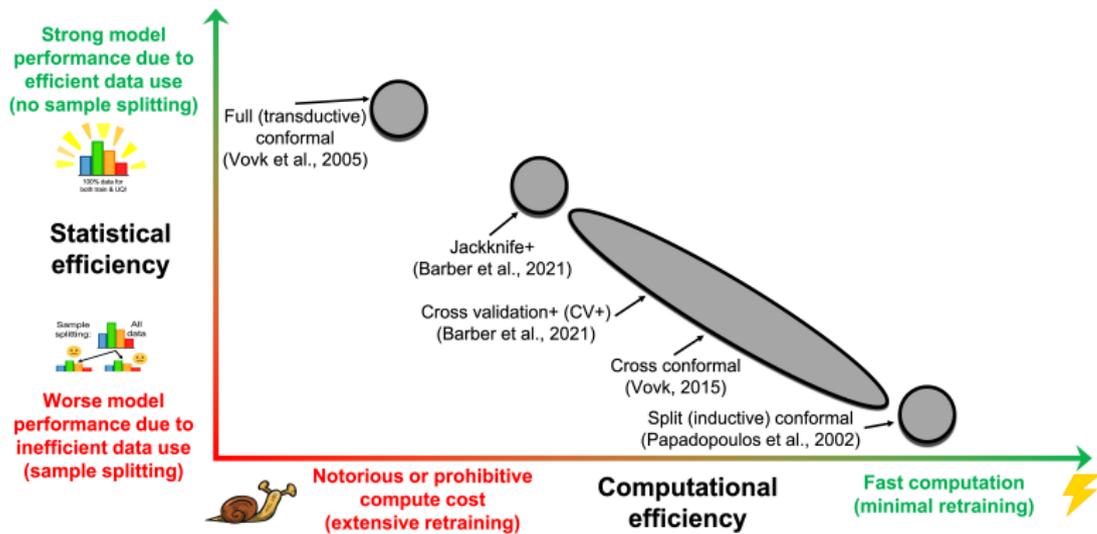
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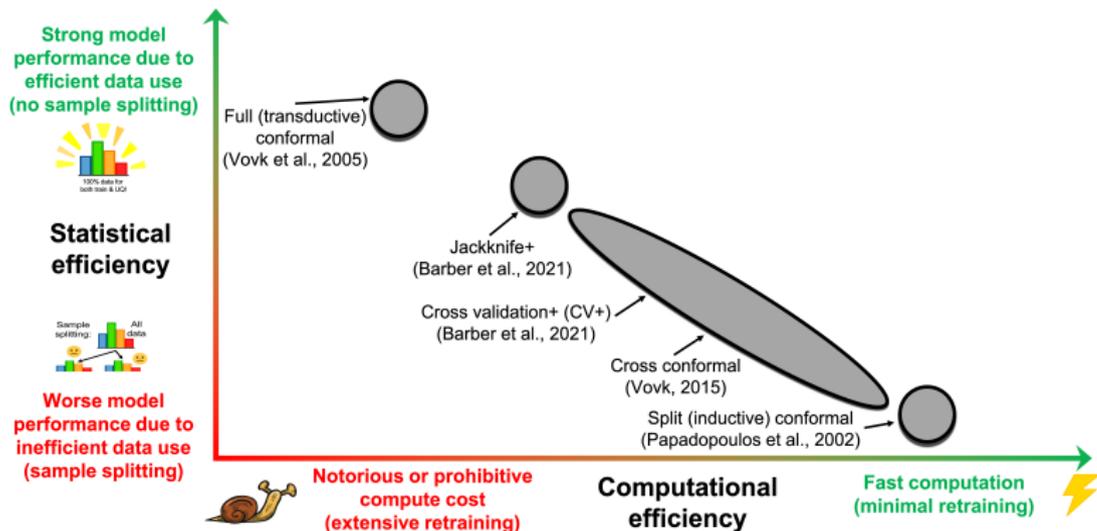
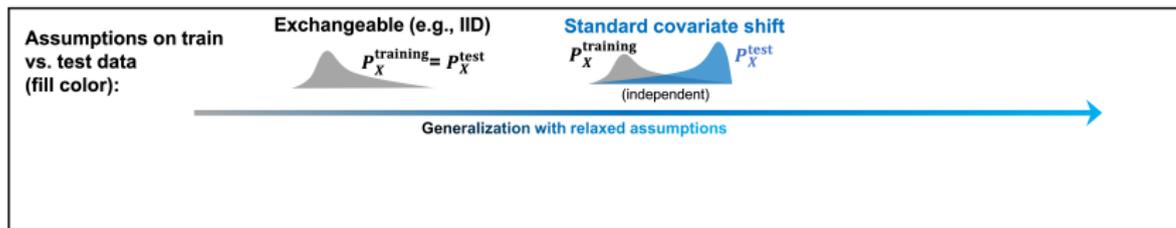
Related Work: Efficiency Tradeoffs

Assumptions on train vs. test data:

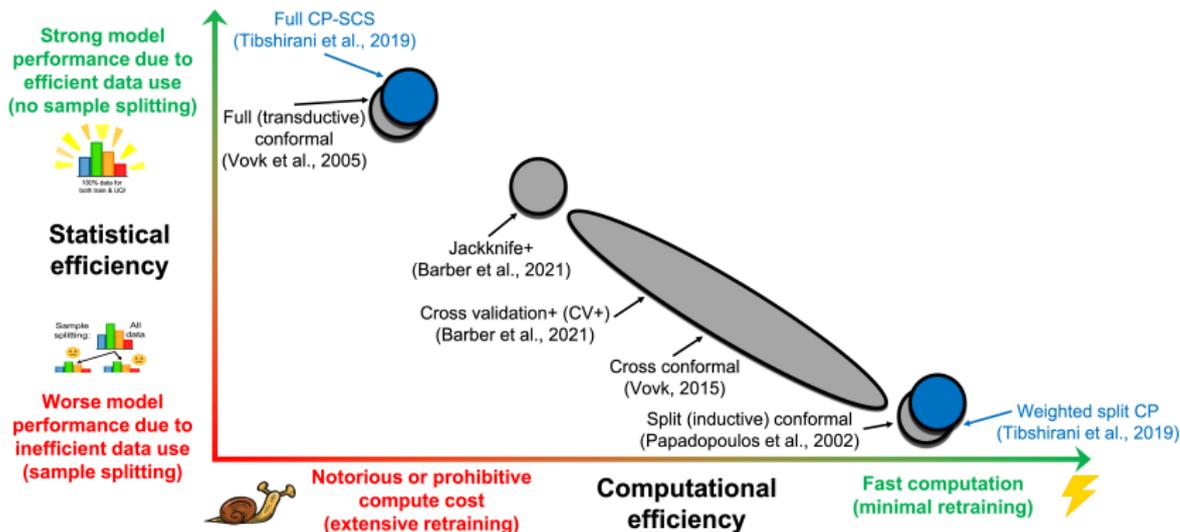
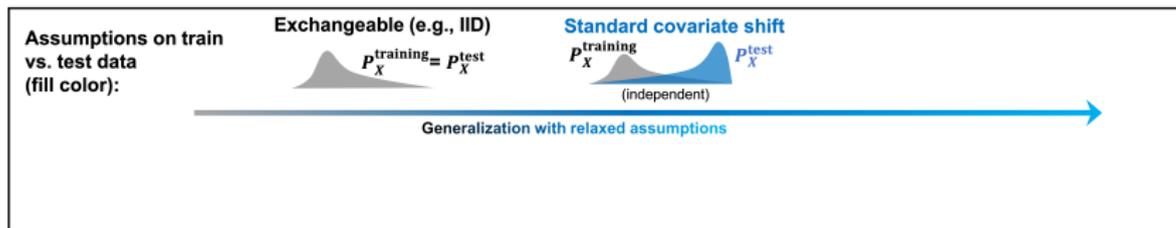
Exchangeable (e.g., IID)

$$P_X^{\text{training}} = P_X^{\text{test}}$$


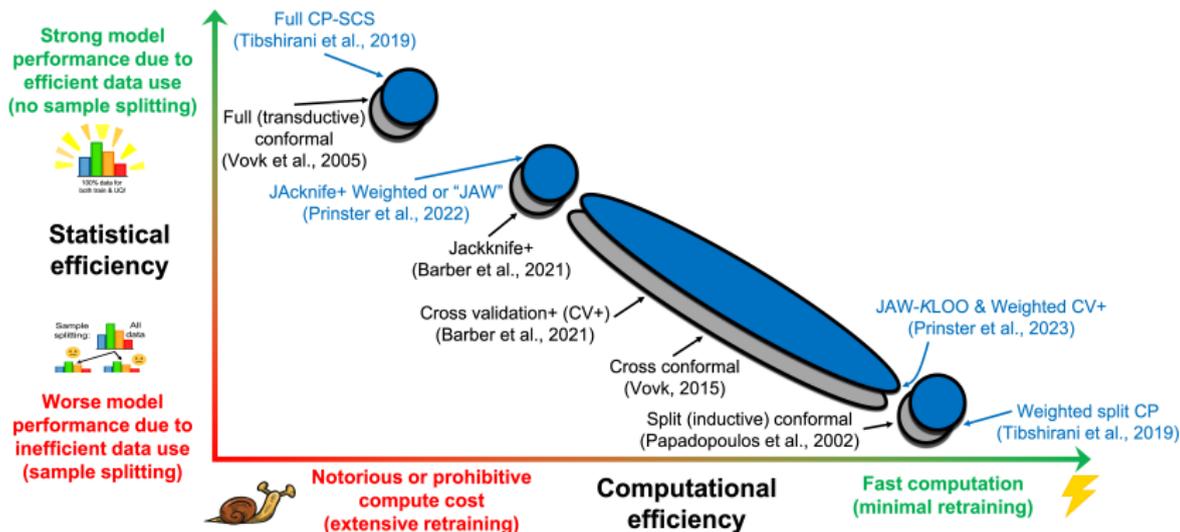
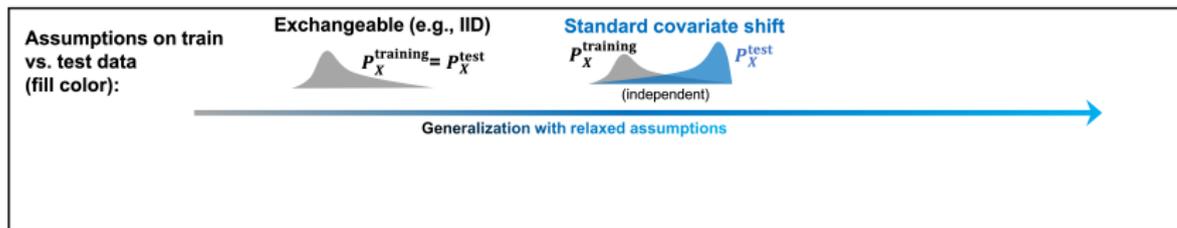
Related Work: Feedback Covariate Shift (FCS)



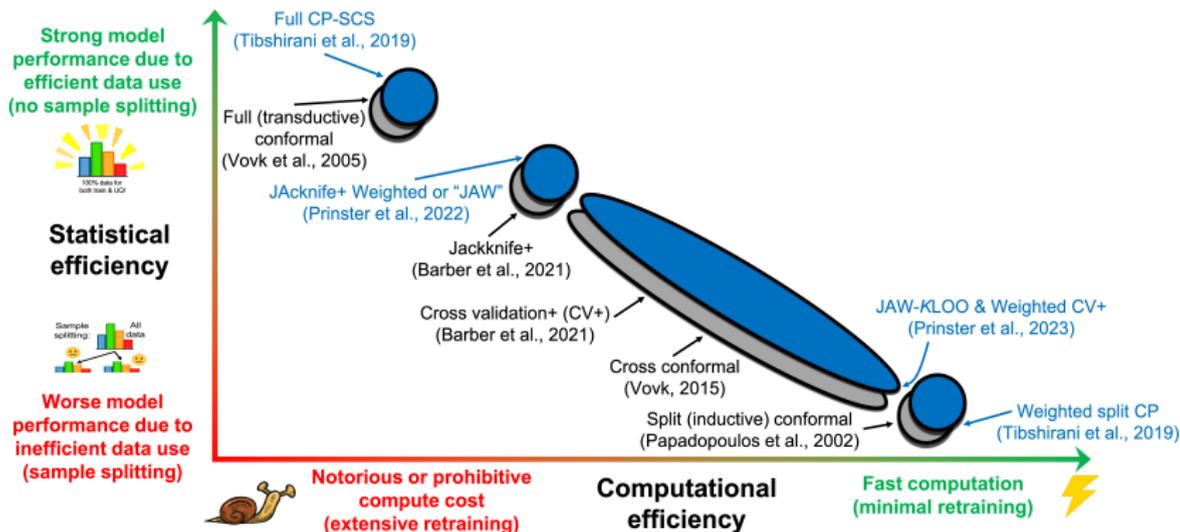
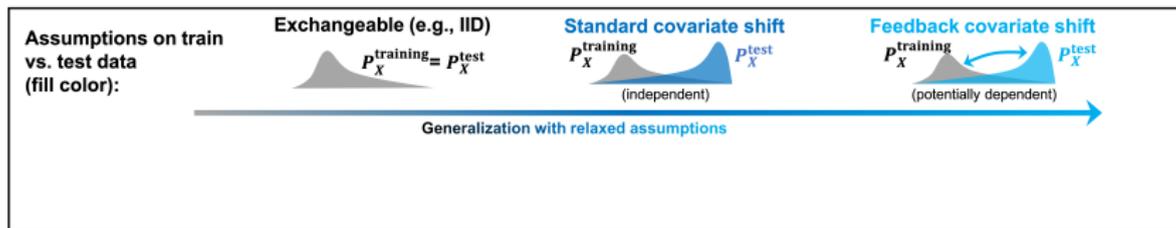
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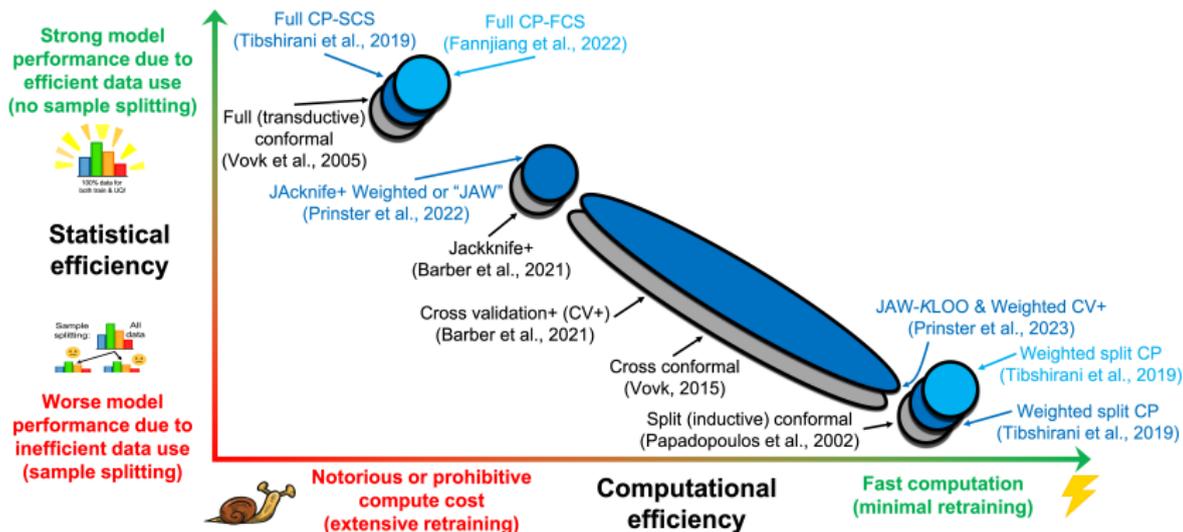
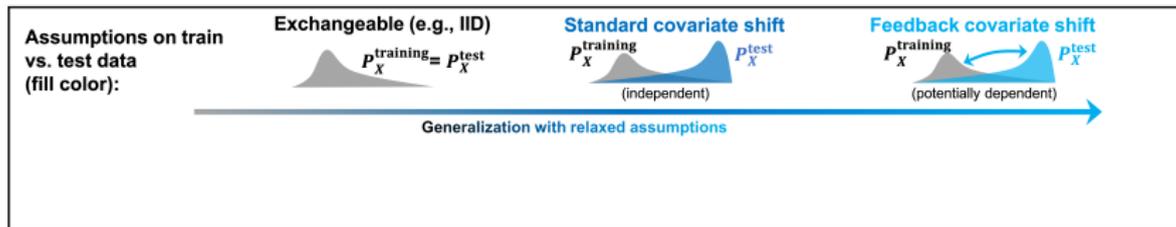
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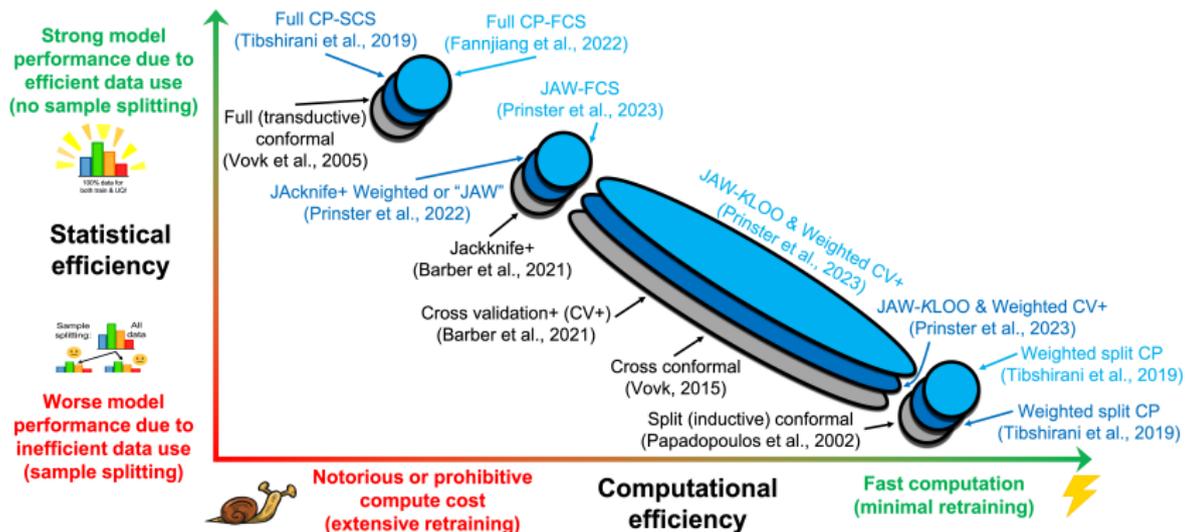
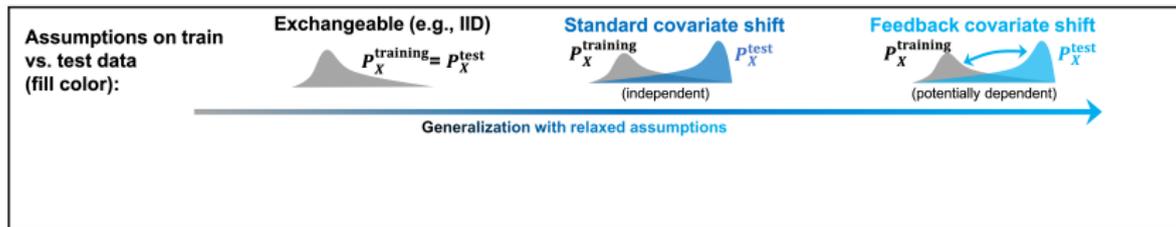
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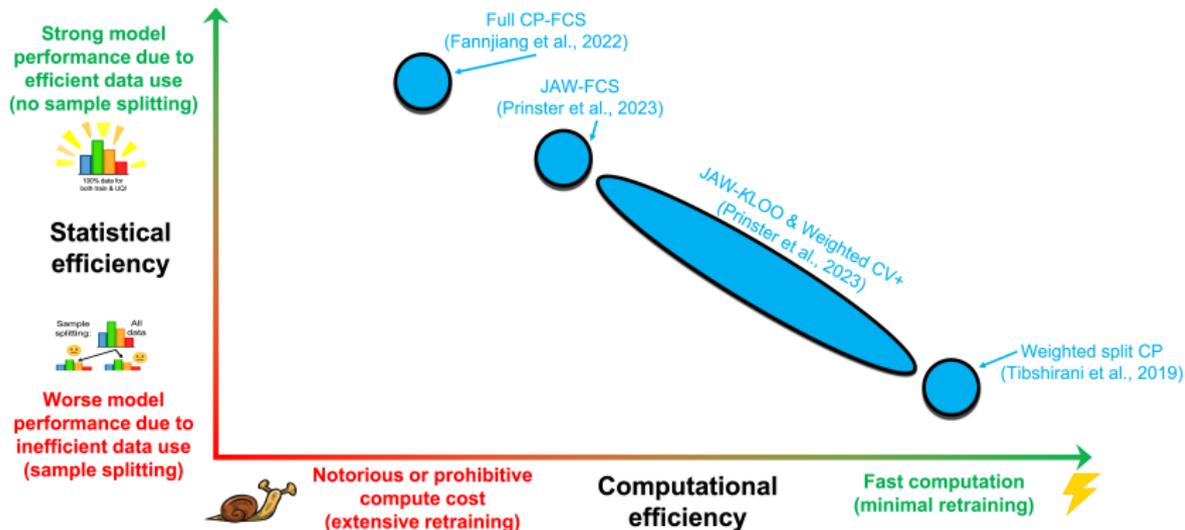
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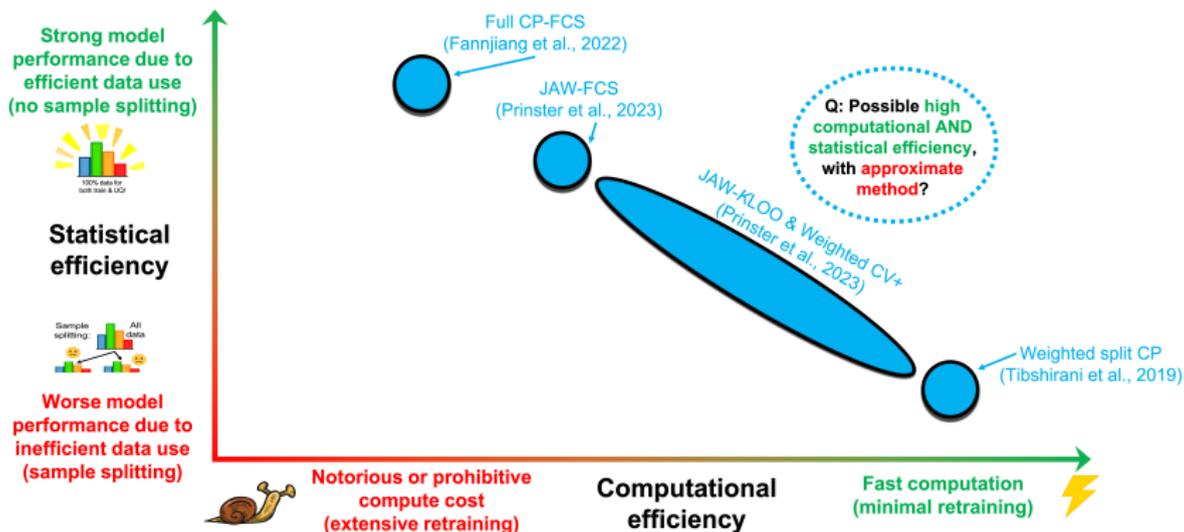
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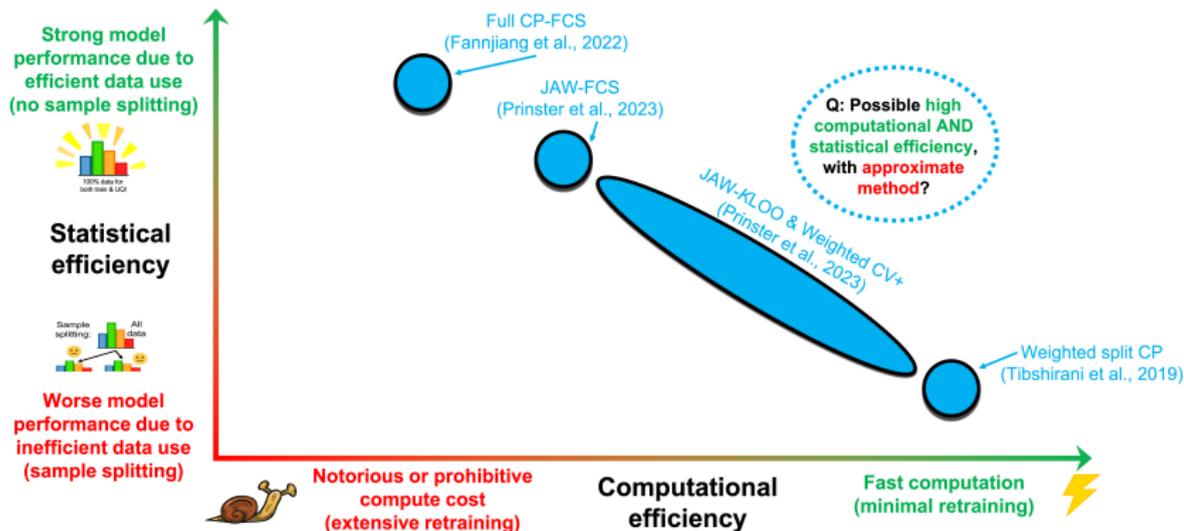
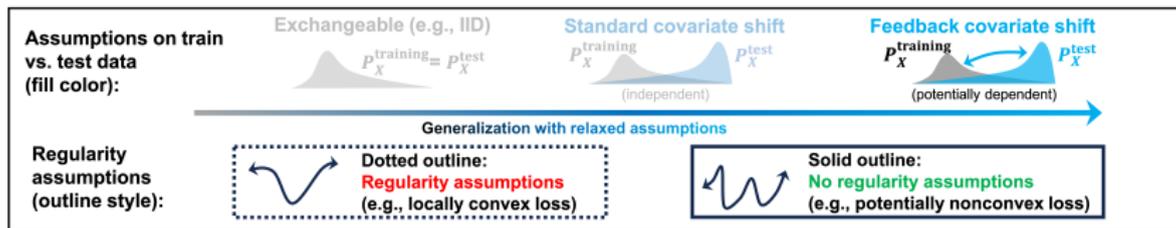
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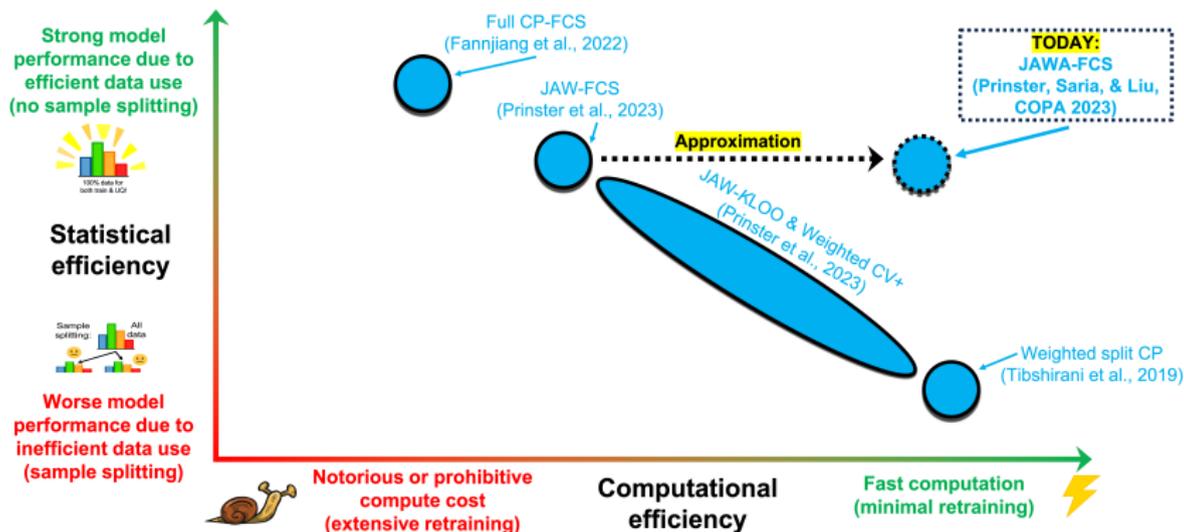
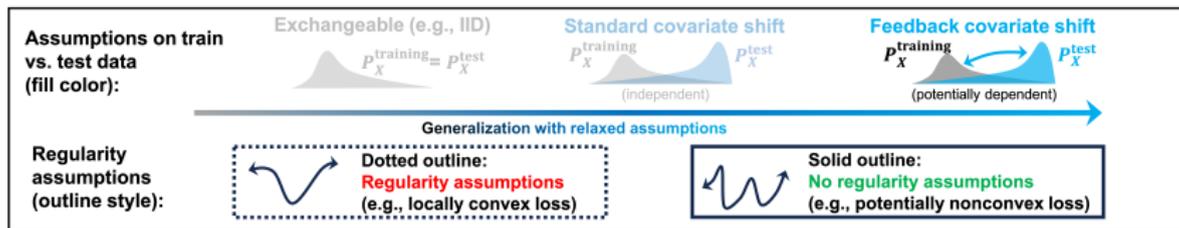
Related Work: Feedback Covariate Shift (FCS)



Proposed Work: Approximation of JAW-FCS

Related Work: High-Level Overview

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Background: Jackknife+ Predictive Interval

Jackknife+ predictive interval (Barber, Candes, Ramdas, & Tibshirani, 2021):

$$\hat{C}_{n,\alpha}^{\text{Jackknife}+}(x) = \left[Q_{\alpha} \left(\sum_{j=1}^n \frac{1}{n+1} \delta_{\hat{\mu}_{-j}(x) - |Y_j - \hat{\mu}_{-j}(X_j)|} + \frac{1}{n+1} \delta_{-\infty} \right), \right. \\ \left. Q_{1-\alpha} \left(\sum_{j=1}^n \frac{1}{n+1} \delta_{\hat{\mu}_{-j}(x) + |Y_j - \hat{\mu}_{-j}(X_j)|} + \frac{1}{n+1} \delta_{\infty} \right) \right]$$

Some notation:

- $\delta_v :=$ point mass at value v
 - $\hat{\mu}_{-j} :=$ Leave-one-out (LOO) retrained model
- \Rightarrow Requires training n distinct predictors

Background: JAckknife+ Weighted for FCS

(Fitted) likelihood ratio weights:

$$w(x; D) = \frac{dP_{X;D}^{\text{test}}(x)}{dP_X^{\text{train}}(x)}$$

e.g.,
 $P_{X;D}^{\text{test}}(x) \propto \exp(\lambda \cdot \hat{\mu}(x))$

Normalized weights:

$$\tilde{w}_{n+1,j}(x) = \frac{\overbrace{w(x; Z_{-j})w(X_j; Z_{-j})}^{\text{weights for LOO pt } j \text{ and test pt } n+1}}{\underbrace{\sum_{j'=1}^n [w(x; Z_{-j'})w(X_{j'}; Z_{-j'})] + w(x; Z_{1:n})^2}_{\text{normalization constant}}}$$

JAckknife+ **W**eighted for **F**eedback **C**ovariate **S**hift or “**JAW-FCS**”
(Prinster, Liu, & Saria, 2023):

$$\hat{C}_{n,\alpha}^{\text{JAW-FCS}}(x) = \left[Q_\alpha \left(\sum_{j=1}^n \tilde{w}_{n+1,j}(x) \delta_{\hat{\mu}_{-j}(x) - |Y_j - \hat{\mu}_{-j}(X_j)|} + \tilde{w}_{(n+1)}^2(x) \delta_{-\infty} \right), \right. \\ \left. Q_{1-\alpha} \left(\sum_{j=1}^n \tilde{w}_{n+1,j}(x) \delta_{\hat{\mu}_{-j}(x) + |Y_j - \hat{\mu}_{-j}(X_j)|} + \tilde{w}_{(n+1)}^2(x) \delta_{\infty} \right) \right]$$

Note: Often $w(\cdot; Z_{-j})$ and $\hat{\mu}_{-j}$ require the same LOO parameter est. $\hat{\theta}_{-j}$

Background: Influence Functions

Influence functions (Cook, 1977; Giordano, Jordan, & Broderick, 2019) approximate model parameter changes due to removing (or reweighting) a datapoint via a K -th order Taylor series.

$$\hat{\theta}_{-i}^{\text{IF-}K} := \hat{\theta} + \sum_{k=1}^K \frac{1}{k!} D_{-i}^k \hat{\theta}$$

$D_{-i}^k \hat{\theta} := k$ th order derivative of parameters $\hat{\theta}$ w.r.t. removing point i

Main computational cost: Computing inverse Hessian

Prior works using IFs with jackknife+:

- Alaa and Van Der Schaar (2020) used higher order IFs to approximate the Jackknife+, but assume i.i.d. data
- Prinster, Liu, and Saria (2022) used higher orders to approximate the JAckknife+ Weighted for *Standard* Covariate Shift (JAW-SCS), but with different weights than in FCS

Proposed Method: JAWA-FCS

JAWA-FCS: JAckknife **W**eighted **A**pproximation for **F**eedback **C**ovariate Shift (K -th order Influence Function)

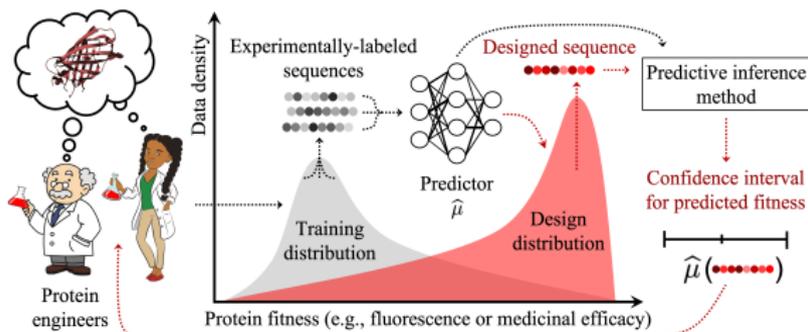
$$\begin{aligned} \hat{C}_{n,\alpha}^{\text{JAWA-FCS}}(\mathbf{x}) &= \left[Q_{\alpha} \left(\sum_{j=1}^n \tilde{w}_{n+1,j}^{\text{IF-K}}(\mathbf{x}) \delta_{\hat{\mu}_{-j}^{\text{IF-K}}(\mathbf{x}) - |Y_j - \hat{\mu}_{-j}^{\text{IF-K}}(X_j)|} + \tilde{w}_{(n+1)^2}^{\text{IF-K}}(\mathbf{x}) \delta_{-\infty} \right), \right. \\ &\quad \left. Q_{1-\alpha} \left(\sum_{j=1}^n \tilde{w}_{n+1,j}^{\text{IF-K}}(\mathbf{x}) \delta_{\hat{\mu}_{-j}^{\text{IF-K}}(\mathbf{x}) + |Y_j - \hat{\mu}_{-j}^{\text{IF-K}}(X_j)|} + \tilde{w}_{(n+1)^2}^{\text{IF-K}}(\mathbf{x}) \delta_{\infty} \right) \right] \end{aligned}$$

Main idea: Approximating both the weights $w(\cdot; Z_{-j})$ and LOO predictions $\hat{\mu}_{-j}$ using influence functions (IFs)

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Experiments: Fluorescent Protein Design Task



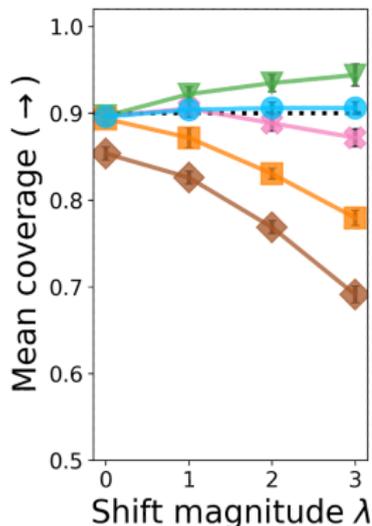
Experimental details:

- $\hat{\mu}$: Small (25 hidden unit) neural network regressor with tanh activation function
- 0.5 L2 regularization parameter
- $n = 192$ training samples
- $K = 3$ rd order influence function approximation
- $\alpha = 0.1$
- 20 experimental replicates

Runtime results: **JAWA-FCS: <3 minutes** **JAW-FCS: 1 hour 24 minutes**

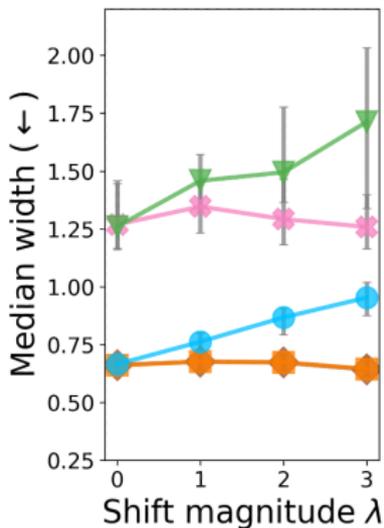
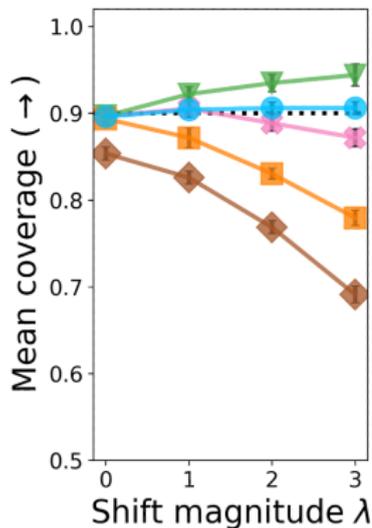
Flourescent Protein Design Results

Proposed



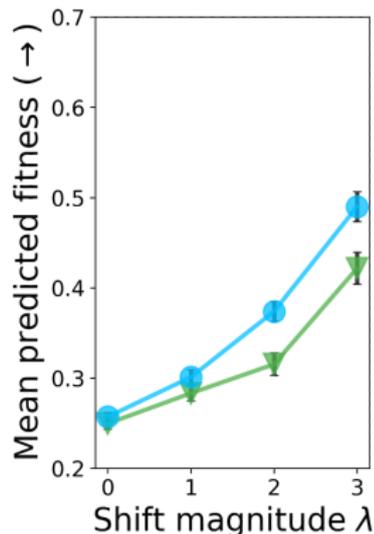
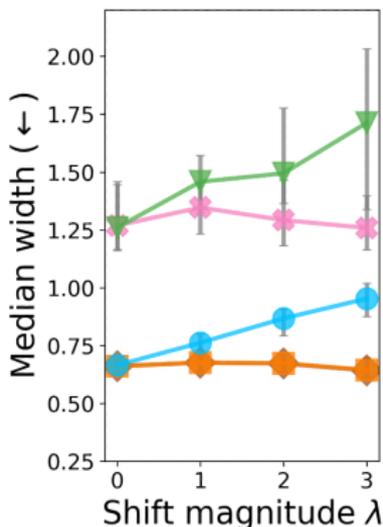
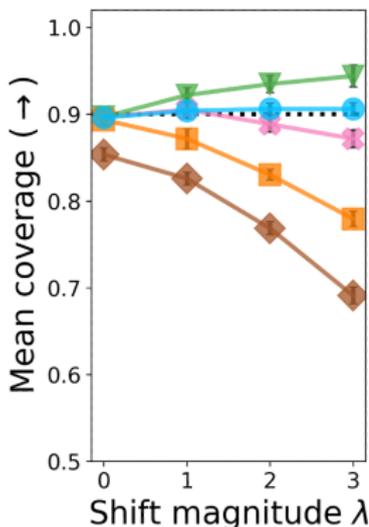
Flourescent Protein Design Results

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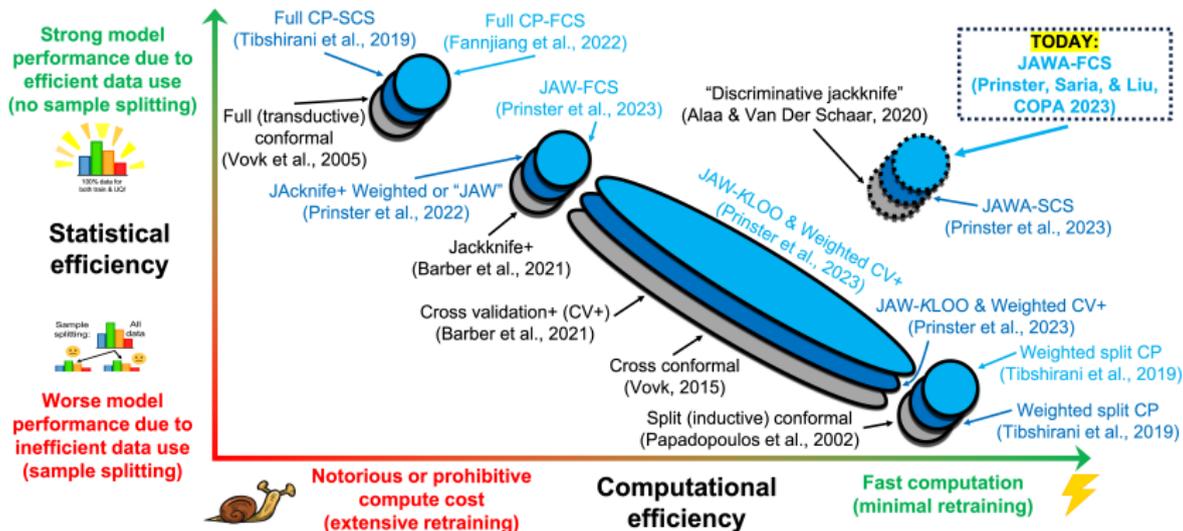
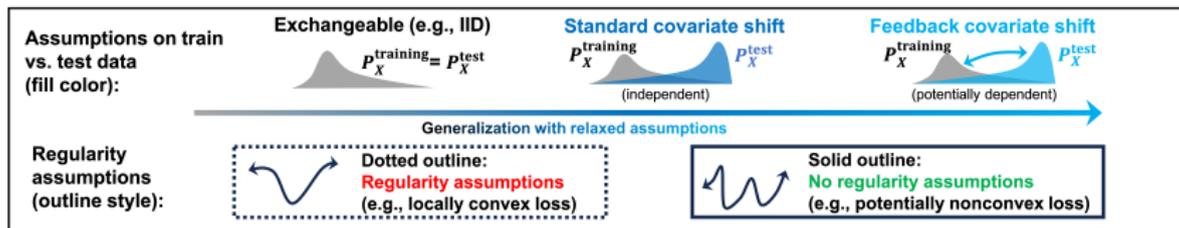
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Limitations and future directions:

- Experiments only with small neural net $\hat{\mu} \Rightarrow$ See if results scale to larger $\hat{\mu}$
- Empirical contribution only \Rightarrow See how IF approximation error would impact guarantees.
- E.g., Giordano et al. (2019) give consistency conditions for LOO IF approximation (but do not consider guarantees for prediction estimates or coverage):
 - $\hat{\theta}$ is local minimum of objective function
 - Existence and boundedness of higher-order derivatives
 - Objective is strongly convex in neighborhood of $\hat{\theta}$

Today's Contribution in Context (Visually)



- Alaa, A., & Van Der Schaar, M. (2020). Discriminative jackknife: Quantifying uncertainty in deep learning via higher-order influence functions. In *International conference on machine learning* (pp. 165–174).
- Barber, R. F., Candes, E. J., Ramdas, A., & Tibshirani, R. J. (2021). Predictive inference with the jackknife+. *The Annals of Statistics*, 49(1), 486–507.
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Thank you!!

