On Training Locally Adaptive Conformal Predictors

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outline

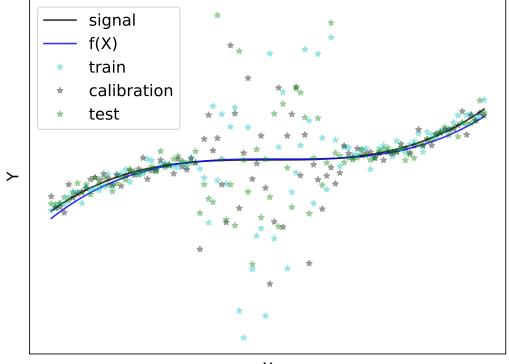
localizing CP

conformity scores

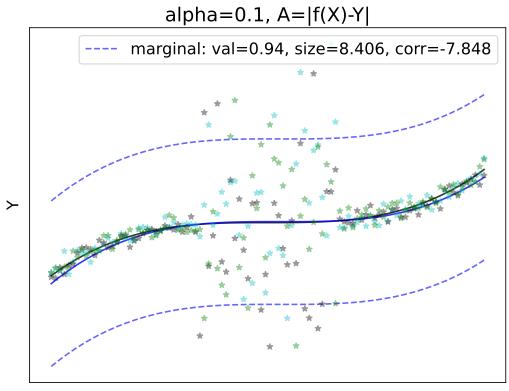
training

discussion

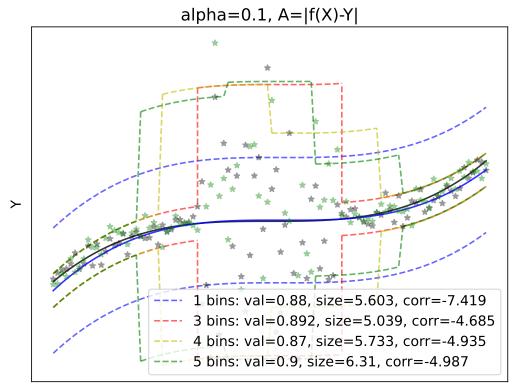
we have good point-prediction model $f(X) \approx \mathsf{E}_{Y|X}(Y)$



marginal prediction intervals (PI) are not efficient



locally-defined PI may be do *better*



locally-defined PI approximate the *ideal* conditional validity $Drah(V = C \cap V) > 1$

 $\mathsf{Prob}(Y_{test} \in C | X_{test}) \ge 1 - \alpha$

how to define the bins? what if somewhere the calibration set gets too small?

instead of partitioning the data, we *localize* the conformity function

$$A(Y, f(X)) \rightarrow B(A, X) = \phi_X(A)$$

to avoid overfitting, $\phi_X(A)$ has a globally defined functional form

predictions on different locations are evaluated *differently*, e.g. $A' < A \Rightarrow \phi_{X'}(A') < \phi_X(A)$

the PI now depend on the transformed calibration set

$$\{B_n = \phi_{X_n}(|Y_n - f(X_n)|)\}_{n=1}^N$$

let Q_B be the $(1 - \alpha)$ th sample quantile of $\{B_n = \phi_{X_n}(|f(X_n) - Y_n|)\}_{n=1}^N$, i.e.

$$Q_B$$
 is such that $|\{B_n \leq Q_B\}_{n=1}^N| = \lceil (1-\alpha)N \rceil$

in the B-space, we have standard marginal PI

$$C_B = \{b \in \mathbb{R}, b \le Q_B\}$$

in the label space, C_B becomes locally-adaptive

$$C_B \sim C = \{ y \in \mathbb{R}, |y - f(X_{test})| \le \phi_{X_{test}}^{-1}(Q_B) \}$$

= $[f(X_{test}) - \phi_{X_{test}}^{-1}(Q_B), f(X_{test}) + \phi_{X_{test}}^{-1}(Q_B)]$

an example from the literature is the Locally Reweighted (LR) CP algorithm

$$B = \phi_X = \frac{A}{g^2(X) + \gamma}, \quad g(X) \approx \mathsf{E}_{A|X}(A), \quad \gamma > 0$$

intuitively, LR *works* because B is almost uniformely distributed for all X

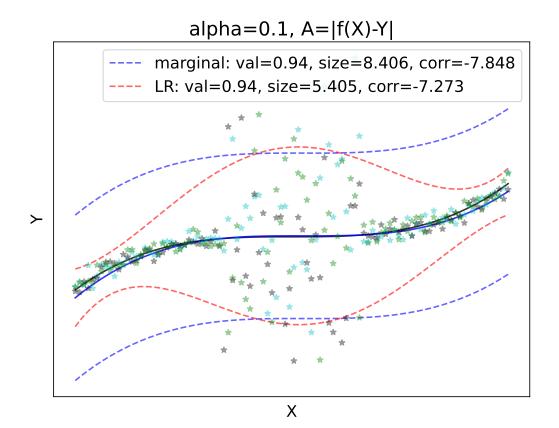
the label-space PI are

$$C = [f(X_{test}) - \phi_{X_{test}}^{-1}(Q_B), f(X_{test}) + \phi_{X_{test}}^{-1}(Q_B)]$$

which have locally-adaptive sizes

$$|C| = Q_B(g^2(X_{test}) + \gamma)$$

the obtained PI are marginally valid by construction



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we *extend* the LR idea in two ways

1 - we let $\phi_X(A)$ be general monotonic functions of A

2 - we train ϕ_X to maximize the efficiency of the PI

i.e. we define a model class $\Phi = \{\phi_X(A,\theta), X \in \mathcal{X}, \theta \in \mathbb{R}^d\}$ and minimize the average size of the PI

$$\ell_{\text{size}}(\theta) = \mathsf{E}_{\alpha, X_{test}, D_{cal}}\left(\phi_{X_{test}}^{-1}(Q_B, \theta)\right)$$

for example, let

$$\phi_X = A\sigma(\theta_1(1 - \theta_2 X^2)), \quad \sigma(t) = \frac{1}{1 + e^{-t}}$$

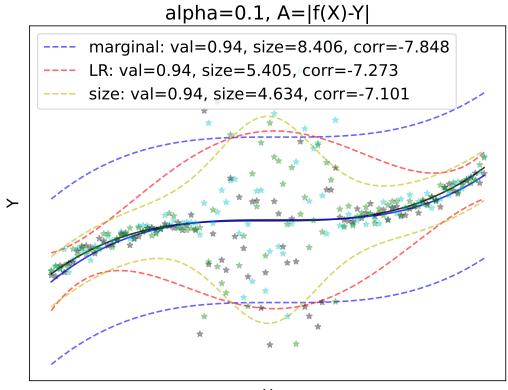
and search for the *optimal* $\theta = (\theta_1, \theta_2)$

 $\sigma(\theta_1(1-\theta_2 X^2))$ does *not* need to be a model of the conditional residuals

the obtained locally-adaptive PI are

$$C = \left\{ y \in \mathbb{R}, |f(X) - y| \le \frac{Q_B}{\sigma(\theta_1(1 - \theta_2 X^2))} \right\}$$

again, the PI are marginally valid by construction



we obtain θ by minimizing

$$\ell_{\text{size}}(\theta) \approx \sum_{n \neq n'} \phi_{X_n}^{-1} \left(\phi_{X_{n'}}(A_{n'}, \theta), \theta \right) = \sum_{n \neq n'} A_{n'} \frac{\sigma(\theta_1(1 - \theta_2 X_{n'}^2))}{\sigma(\theta_1(1 - \theta_2 X_n^2))}$$

with gradient descent updates *

$$\theta \leftarrow \theta - \eta \sum_{n \neq n'} d\phi_{X_n}^{-1} \left(\phi_{X_{n'}}(A_{n'}, \theta), \theta \right)$$

the derivatives of ϕ_X^{-1} are obtained implicitly from $d_\theta \phi_X^{-1}(\phi_X(A,\theta)) = 0$

and

$$\partial_B \left(\phi_X \left(\phi_X^{-1}(B, \theta), \theta \right) \right) = 1$$

 $^*d(\psi\circ\zeta)=\nabla\psi\circ\zeta+(\psi'\circ\zeta)\,\nabla\zeta$

how flexible is the scheme?

other possible model classes are

 $\phi_X = A \exp(g(X)), \quad \phi_X = \log A + g(X), \quad \phi_X = \sigma(\log A + g(X))$

the models fulfil a domain-codomain assumption

$$\phi_X : \mathbb{R}_+ \to \mathcal{B}, \quad \phi_X^{-1} : \mathcal{B} \to \mathbb{R}_+ \text{ for all } X$$

for example, $\phi_X = \sigma(A+g^2(X))$ is not allowed because logit($\sigma(A+g^2(X)) - g^2(X')$ may be negative for some $X, X' \in \mathbb{R}$ and A = |f(X) - Y|

thank you!