Sleeping Experts in On-line Prediction

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Protocol

Contents

- we try to predict elements of a sequence $\omega_1, \omega_2, \omega_3, \ldots \in \Omega$
- we output predictions $\gamma_1, \gamma_2, \gamma_3, \ldots \in \Gamma$
- we can make use of signals $s_1, s_2, s_3 \dots$
- protocol:

FOR
$$t = 1, 2, ...$$

1. Aggregating Algorithm

3. An Application to Implied Volatility

2. Sleeping Experts

4. Examination Results

- (1) Learner observes signal s_t
- (2) Learner chooses a prediction $\gamma_t \in \Gamma$
- (3) Learner observes the actual outcome $\omega_t \in \Omega$
- (4) Learner suffers loss $\lambda(\omega_t, \gamma_t)$

END FOR

• loss over T trials sums up to the cumulative loss

$$\mathsf{Loss}(\omega_1,\omega_2,\ldots,\omega_{\mathcal{T}}) = \sum_{i=1}^{\mathcal{T}} \lambda(\omega_i,\gamma_i)$$

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1. Aggregating Algorithm

Formalisation

- a game \mathfrak{G} is a triple $\langle \Omega, \Gamma, \lambda \rangle$
 - $\diamond \Omega$ is the *outcome space*
 - $\diamond \Gamma$ is the *prediction space*
 - $\diamond \lambda : \Omega \times \Gamma \to [0, +\infty]$ is the *loss function*
- important special case: binary games
 - $\Diamond \Omega = \mathbb{B} = \{0,1\}$
 - $\diamond \Gamma = [0, 1]$

Examples

- square-loss game: $\Omega = \{0, 1\}, \Gamma = [0, 1], \lambda(\omega, \gamma) = (\omega \gamma)^2$
- absolute-loss game: $\Omega = \{0,1\}, \Gamma = [0,1], \lambda(\omega,\gamma) = |\omega-\gamma|$
- logarithmic game: $\Omega = \{0, 1\}, \Gamma = [0, 1]$

$$\lambda(\omega,\gamma) = \left\{ egin{array}{ll} -\log_2(1-\gamma) & ext{if} & \omega=0 \ -\log_2\gamma & ext{if} & \omega=1 \end{array}
ight.$$

— can take the value $+\infty$

• simple prediction game: $\Omega = \Gamma = \{0, 1\}$

$$\lambda(\omega,\gamma) = \left\{ egin{array}{ll} 0 & ext{if} & \omega = \gamma \ 1 & ext{if} & \omega
eq \gamma \end{array}
ight.$$

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Experts

• suppose that we can see predictions of N Experts E_1, E_2, \ldots, E_N

FOR t = 1, 2, ...

- (1) Experts output $\gamma_t^n \in \Gamma$, n = 1, ..., N
- (2) Learner outputs $\gamma_t \in \Gamma$
- (3) the outcome $\omega_t \in \Omega$ occurs
- (4) Learner suffers loss $\lambda(\gamma_t, \omega_t)$
- (5) Experts suffer losses $\lambda(\gamma_t^n, \omega_t)$, n = 1, 2, ..., N

END FOR

• we want to be sure not to suffer loss much greater than that of the best expert

— i.e., we want a guarantee of the type Loss $(T) \leq \text{Loss}_{F_n}(T)$ for all n and T

Aggregating Algorithm

- takes a parameter $\eta > 0$ (learning rate)
- maintains weights w_t^n for experts — they are initialised with a distribution q_1, q_2, \ldots, q_N (e.g., uniform $q_n = 1/N$
 - after expert E_n suffers loss $\lambda(\gamma_t^n, \omega_t)$, its loss is updated as

$$w_{t+1}^n = w_t^n e^{-\eta \lambda(\gamma_t^n, \omega_t)}$$

• on step t normalised weights $p_t^n = w_t^n / \sum_{m=1}^N w_t^m$ are used to work out Learner's prediction γ_t satisfying

$$\lambda(\gamma_t,\omega) \leq -C(\eta) \frac{1}{\eta} \ln \sum_{n=1}^N p_t^n e^{-\eta \lambda(\gamma_t^n,\omega)}$$

for all $\omega \in \Omega$

• $C(\eta)$ is the smallest number such that γ_t can always be found

Algorithm

parameters: η and initial distribution q_1, q_2, \ldots, q_N

- (1) initialise $w_1^n = q_n$, n = 1, 2, ..., NFOR t = 1, 2, ...
 - (2) read experts' predictions γ_t^n , n = 1, 2, ..., N
 - (3) normalise weights $p_t^n = w_t^n / \sum_{n=1}^N w_t^n$
 - (4) solve the system $(\omega \in \Omega)$: $\lambda(\gamma, \omega) \leq -\frac{C(\eta)}{\eta} \ln \sum_{n=1}^{N} p_t^n e^{-\eta \lambda(\gamma_t^n, \omega)}$ w.r.t. γ and output γ_t
 - (5) observe ω_t
- (6) update experts' weights $w^n_{t+1}=w^n_t e^{-\eta \lambda(\gamma^n_t,\omega)}$, $n=1,2,\ldots,N$ END FOR

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The Guarantees

• for all sequences of outcomes $\omega_1, \omega_2, \ldots$ and experts' predictions and every $n = 1, 2, \ldots, N$ we get

$$\mathsf{Loss}(t) \leq \mathit{C}(\eta) \, \mathsf{Loss}_{\mathit{E}_n}(t) + rac{\mathit{C}(\eta)}{\eta} \, \mathsf{ln} \, rac{1}{q_n}$$

— if the initial weights are uniform

$$\mathsf{Loss}(t) \leq C(\eta) \, \mathsf{Loss}_{E_n}(t) + rac{C(\eta)}{\eta} \, \mathsf{In} \, \mathcal{N}$$

• if $C(\eta) =$ for some η , the game is called *mixable* — for mixable games we get

$$\mathsf{Loss}(t) \leq \mathsf{Loss}_{E_n}(t) + rac{\mathsf{ln} \; \mathsf{N}}{\eta}$$

• the coefficients $C(\eta)$ and $C(\eta)/\eta$ are optimal

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Definition

- suppose that an expert can skip turns...
- a *specialist expert* can refrain from prediction on step *t*
 - if it makes a prediction, we say that it is awake
 - otherwise we say that it *sleeps*
 - specialist experts *can sleep* a sleeping expert *is sleeping* now
- how can we handle them?
 - idea: let a sleeping expert follow awake ones
- literature:
- originated in [Y. Freund et al, Using and combining predictors that specialize, Proceedings of STOC 1997]
- we follow [A.Chernov and V.Vovk, Prediction with expert evaluators' advice, Proceedings of ALT 2009]

Algorithm (1)

look at

$$e^{-\eta\lambda(\gamma_t,\omega)} \geq \sum_{n=1}^N p_t^n e^{-\eta\lambda(\gamma_t^n,\omega)}$$

- this is the exponentiated key inequality of the aggregating algorithm for the mixable case
- let us single out the terms corresponding to sleeping and awake experts

$$e^{-\eta\lambda(m{\gamma_t},\omega)} \geq \sum_{n:E_n ext{ is awake}} p_t^n e^{-\eta\lambda(m{\gamma_t}^n,\omega)} + \sum_{n:E_n ext{ sleeps}} p_t^n e^{-\eta\lambda(m{\gamma_t},\omega)}$$

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Loss Bound

in

$$\mathsf{Loss}(T) \le \mathsf{Loss}_{E_n}(T) + \frac{1}{\eta} \ln N$$

we can drop the terms where E_n sleeps

• we get

$$\overline{\mathsf{Loss}}^n(T) \leq \overline{\mathsf{Loss}}^n_{E_n}(T) + \frac{1}{\eta} \mathsf{In} \, N$$

where the sum in $\overline{\text{Loss}}^n$ is taken over steps where E_n was awake

Algorithm (2)

• the sum over sleeping experts cancels out

$$e^{-\eta\lambda(\gamma_t,\omega)} \geq rac{1}{Z_t} \sum_{n:E_n ext{ is awake}} p_t^n e^{-\eta\lambda(\gamma_t^n,\omega)}$$

where Z_t is the weight of experts awake on step t

- specialist experts can be handled with a minimum modification of the algorithm:
 - the summation is done over awake experts and their weights are normalised to $\boldsymbol{1}$
 - the sleeping experts output "the crowd's" prediction γ_t , and so their weights are updated as $w_{t+1}^n = w_t^n e^{-\eta \lambda (\gamma_t, \omega_t)}$ using the Learner's γ_t

Discussion

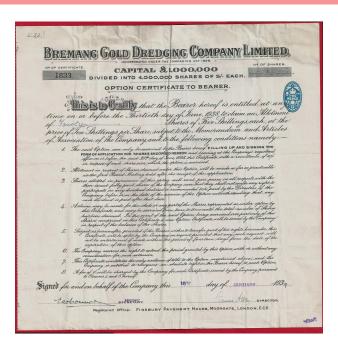
- new experts can be added on-the-fly
 e.g., a new expert can start predicting upon completing a training stage
- the weight of a new expert joining at time T can be worked out using our loss Loss(T-1), because it was following us while it was sleeping
- sleeping experts can be used to extract relevant historical information

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Options

• an option on a share is a contract of the following kind:

The bearer of this may buy a share of ABC

Itd in December 2014 at a price of \$10.

buy: an option that entitles its holder to buy at a fixed price is called *call*, and an option that entitles to sell is called *put*

share: the financial instrument that is bought or sold is called *the* underlying (asset); it can be a share, a futures, an index etc.

Dec 2014: the option shows the date when it can be *exercised*, i.e., when the holder may use it; it is called *maturity* or *expiration* (it makes sense to exercise this option if and only if the share price in December 2014 exceeds \$10)

— the stock exchange usually fixes four expiration dates in a

— the stock exchange usually fixes four expiration dates in a year and only allows options with those expiration dates

\$10: the fixed price written in the option is called strike

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Mathematical Interpretation

call option:

The bearer of this is entitled to the sum of $\max(S_T - X, 0)$ at the moment T.

• put option:

The bearer of this is entitled to the sum of $\max(X - S_T, 0)$ at the moment T.

• here:

T – expiration moment

 S_T – the price of the underlying at time T

X – strike price

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Black-Scholes Formulas

- what is the value of an option?
- call: $c = S\Phi(d_1) Xe^{-rT}\Phi(d_2)$
- put: $p = Xe^{-rT}\Phi(-d_2) S\Phi(-d_1)$

$$d_1 = (\ln(S/X) + (r + \sigma^2/2)T)/(\sigma\sqrt{T})$$

$$d_2 = (\ln(S/X) + (r - \sigma^2/2)T)/(\sigma\sqrt{T})$$

where:

X – strike

T – time of expiration/maturity

S – the price of the underlying

r – interest rate (often taken to be 0)

 σ – volatility

 Φ – the distribution function of the Gaussian distribution

Volatility

- volatility is the only parameter that is not observed directly
- the Black-Scholes(-Merton) theory assumes that the logarithm of the stock price $\ln S_t$ follows the generalised Brownian motion so that the variance of $(\ln S_{t+\Delta t} \ln S_t)$ is $\sigma^2 \Delta t$
- ullet the volatility σ can be estimated statistically from share price observations

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Implied Volatility (1)

- the option price can actually be observed (we can see the quote)
- let us use the B-S formula the other way round and work out the volatility from the option price
- this estimate is called *implied volatility*

Implied Volatility (2)

- the Black-Scholes volatility is specified by the share and therefore does not depend on the option parameters
- in practice the implied volatility does and we get a function $\sigma(X,T)$
 - there is no unique commonly recognised explanation to this
- the graph of $\sigma(X)$ for fixed T is called *volatility smile*
- implied volatility is a commonly used and intuitive (for traders) parameter

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Predicting Implied Volatility

- we are given a log of option transactions (on a fixed underlying with a fixed maturity)
 - the data was provided by the Russian Trading System Stock Exchange
- we want to predict implied volatility for the next transaction
 — we can use the current stock price, strike, and time to maturity (the interest rate is assumed to be 0) but not the option price (as it immediately implies the volatility)
- we use square loss— this is a mixable game (though not binary)
- consider shares of Russian Energy Systems maturing in December 2006 (about 13000 transactions)

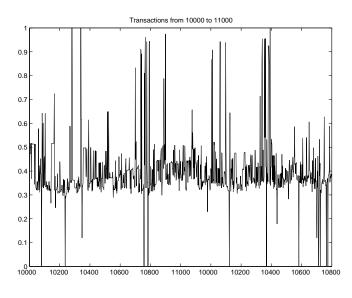
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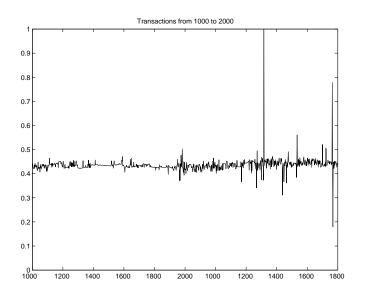
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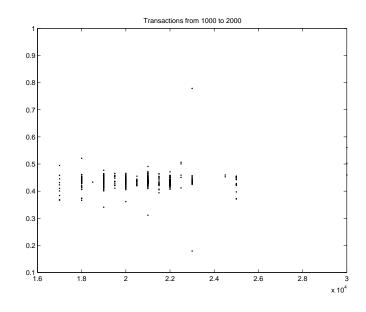
Volatility vs Transaction Number, 10000-11000



Volatility vs Transaction Number, 1000-2000

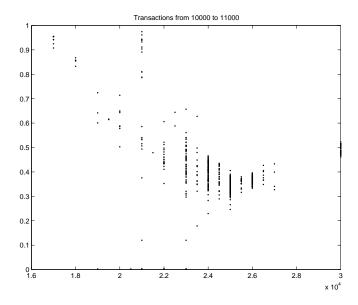


Volatility vs Strike, 1000-2000



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Volatility vs Strike, 10000-11000



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Vicinities

- for small and for large strikes transactions are few
 - the previous transaction with the same strike may be far away in time
 - is not it better to take a more recent transaction from a neighbouring strike?
- let us consider vicinities of strikes
 - we predict implied volatility using the last transaction from a vicinity
- what is the right size for a vicinity?
 - we should use small vicinities in the middle and larger vicinities on the sides
- but how small and how large?
 - which neighbour is nearer to us, that in time or that in space?

Naive Algorithm

- let us predict implied volatility as the implied volatility from the previous transaction with the same strike
 - the list of transactions splits into separate time series
 - inside every time series we use the "nearest neighbour" approach
- we also used simple smoothing: a moving average with exponentially decreasing weights
 - this yields a slight improvement
- more advanced time series methods gave no improvement

Specialist Experts

- consider all sets of contiguous strikes $\{X_1, X_2, \dots, X_k\}$, where k is a "diameter" parameter
- every vicinity specifies three experts:
 - 1. the expert working on transactions with strikes from this vicinity
 - when it sees a transaction with a strike from the vicinity, it outputs volatility from the previous transaction from the vicinity
 - when it sees a transaction with a strike from outside the vicinity, it sleeps
 - 2. the expert working on transactions with call options with strikes from this vicinity
 - 3. the expert working on transactions with put options with strikes from this vicinity

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Results

- the following options were considered:
 - 1. Options on shares of Russian Energy Systems maturing in December 2006, 13K transactions
 - 2. Options on shares of Gazprom maturing in March 2007, 11K transactions
 - 3. Options on the RTSSE index (index is a portfolio of a special type) maturing in March 2007, 8.5K transactions
- we plot the adjusted loss

$$Loss(T) - Loss_{RTSSE}(T)$$

where $\mathsf{Loss}_{\mathsf{RTSSE}}(T)$ is the loss of a proprietary strategy (based on a parametric approximation for $\sigma(X)$)

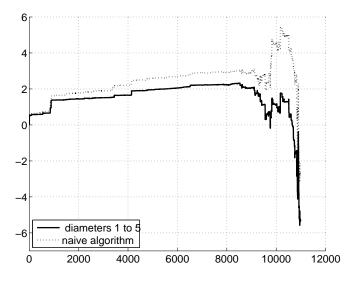
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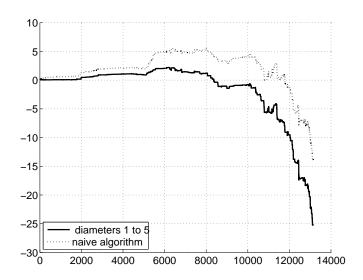
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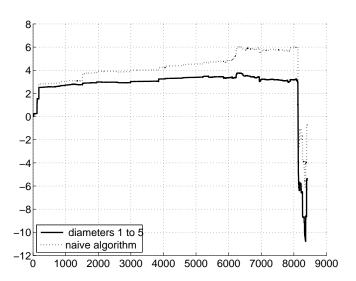
Gazprom



Russian Energy Systems



RTSSE Index



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Discussion (1)

Discussion (2)

- results are comparable to those of a sliding window regression
 - regression is a standard way to model implied volatility
- as the maximum allowed diameter increases, the loss drops and then starts slowly going up
 - the regret is proportional to In(number of experts) and grows very slowly
 - taking to many experts is rarely a problem: the algorithm will converge on the right ones

- vicinities of diameter 5 alone produce a poor result; but adding them to vicinities of sizes 1 to 4 improves the result.
 - even poor predictors work well somewhere

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Dataset

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- a kaggle challenge "What do we know"
- 4.851.475 examples
- each example is a record of a student answering a question

 a log from some system training students for ACT, GMAT,
 and SAT

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Data Fields Game

- timestamp
- student id
- question id
- track, subtrack, tags— what kind of question it is
- outcome: question answered or not

- outcome space $\Omega = \{0, 1\}$
- prediction space $\Gamma = [0, 1]$ — probability of the student answering correctly
- loss function: capped logarithmic loss (\log_{10}) we can think that predictions are truncated to [0.01, 0.99]

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Batch Setup

- all students who answered more than 6 questions are taken
- for each student the stream is cut at a random point > 6; the last record becomes a test example and all later records are discarded
- all remaining records form the kaggle training set
 - we have access to the future (but not for the same student)

Benchmark Method

- for each student there is a parameter α_i (meaning: student's strength)
- for each question there is a parameter β_j (meaning: question difficulty)

$$\mathsf{Pr}(\mathsf{correct\ answer}) = rac{e^{lpha_i - eta_j}}{1 + e^{lpha_i - eta_j}}$$

- the parameters α_i, β_i are fitted on the training set
- this is known as the Rasch model

Batch Results

On-line Mode

- Rasch model mean loss on the kaggle test set is 0.2566
- the leader in kaggle competition achieves 0.2452
- for comparison $\log_{10} 2 = 0.3010$

- we read the dataset example by example predicting the next outcome as we go along
 - we can only do this on the kaggle training set
- no access to the future

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Constant Experts

- take a grid $\{0.1, 0.2, ..., 0.9\}$ of s numbers
- for every <u>student</u> take s experts making constant predictions for this student (irrespective of questions)
 - interpretation: each expert takes a view regarding the student's strength
- for every *question* take *s* experts making constant predictions for this question (irrespective of students)
 - interpretation: each expert takes a view regarding the question difficulty
- we take a uniform prior

Trofimov-Krichevsky

- for large s (s=9 is OK) this is very similar to having a Trofimov-Krichevsky predictor for each student and for each each question
- a T-K is the Bayesian estimate for the probability of success in the Bernoulli model
 - a T-K predictor for student i predicts

the number of correct answers the student has made so far + 1 the number of questions the student has answered so far + 2

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Results A comparison

- on the training set aggregating algorithm with constant experts suffers mean loss per element 0.2532
- on the kaggle test set the mean loss per element is 0.2717
- recall that the Rasch model loss on the kaggle test set is 0.2566

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Tag Experts

- a tag expert watches a particular tag; when it occurs, the expert uses the T-K predictor on the current student predictions on questions with this tag
- a tag expert takes a view that its tag is informative; it represents a particular topic or subject and each student has a fixed strength in that subject
- aggregating algorithm with tag experts is generally inferior but...

 let us pick a retrospectively best constant expert for each question ("true difficulty")

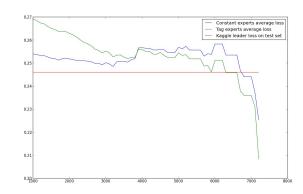
- the mean loss per question is 0.2631
- now let us pick a retrospectively best expert for each student ("true strength")
 - the mean loss per element is 0.2736
- and the loss of the aggregating algorithm is 0.2533

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Loss Structure

- this picture shows loss per element for students who answered more than a particular number of questions
 - the algorithm was still run on the whole dataset; the lower bound on the length is for reporting only
 - at the end averaging includes a small number of students



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